Effects of fatigue on the torque-velocity relation in muscle

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Background: The extent to which fatigue is related to the velocity of shortening is still not fully understood.

Objectives: To examine the effects of fatigue induced by maximal intensity exercise at different velocities on subsequent torque-velocity relations in muscle.

Methods: Ten men [mean (SD) age 25 (3) years; stature 1.78 (0.34) m; body mass 80.6 (14.5) kg] provided written informed consent and, over a five day period in a randomised manner, performed 16 fatiguing bouts of maximal intensity exercise on an isokinetic dynamometer each followed by one repetition maximum action. Concentric peak torque of the preferred leg was assessed at angular velocities of 0.52, 1.05, 2.09, and 3.14 rad/s. Mechanical work performed for all fatiguing bouts was held at 3050–3150 J. After a 45 second rest, a maximum effort was performed at one of the preset velocities. As a baseline, dependent variables of peak torque (N.m), angle of peak torque (rad), and mean torque (N.m) were measured at each velocity. An analysis of covariance was used to compare torque-velocity relations, and one factor, within subject analyses of variance with repeated measures investigated differences from baseline.

Results: Torque-velocity relations for all dependent variables did not differ (p>0.05). Similarly, angles at which peak torque occurred were not velocity dependent and did not differ from baseline and subsequent exercise measures (p>0.05). Generally, fatiguing exercise at low velocities led to reductions in peak and mean torque in subsequent exercise at higher velocities (p<0.05).

Conclusions: Torque-velocity relations fundamentally remain intact after fatigue induced at any velocity, although the magnitude changes. The results suggest that the greater decline in torque during subsequent exercise at high velocities could be due to greater exhaustion of fatigue sensitive type II fibres, whereas low velocity subsequent exercise is less affected because of the greater use of type I fibres.
significance in sport performance, the extent to which fatigue is related to the velocity of shortening is still not fully understood. The purpose of this study was to examine the effects of fatigue induced by maximal intensity exercise at different velocities on subsequent torque-velocity relations in muscle.

METHODS

Subjects
Ten men of mean (SD) age 25 (3) years, stature 1.78 (0.34) m, and body mass 80.6 (14.5) kg volunteered, gave written informed consent, and participated.

Equipment
All procedures were institutionally approved.

Isokinetic dynamometer
All measurements of torque and velocity were made using a Chattecx Kin-Com (Active system, model 125E Plus; Chattanooga Group Inc, Hixson, Tennessee, USA). The apparatus allowed the quadriiceps of each subject's favoured leg to be maximally exercised at preset velocities for a prescribed number of repetitions. Then one maximal effort was measured for peak torque (N.m), angle of peak torque (rad), and mean torque (N.m) for the same velocities. Equipment was calibrated, tested for reproducibility, and data processed through Kin-Com software on a 386 SX-33 MHZ touch screen microcomputer. Baseline and subsequent exercise values were measured using the overlay protocol, and the prior exercise bouts were performed using the continuous protocol.

Dynamometer set up
Testing was performed with participants sitting upright and with the lateral epicondyle of their knee aligned with the axis of the dynamometer's resistance lever. The force pad was placed in a comfortable position across the participant's tibia with the distance of the fulcrum recorded. The hips were stabilised by means of a seat belt while the thigh and ankle were supported by velcro strapping for stabilisation and isolation of the tested muscle group. All bouts of fatiguing and subsequent exercise were measured over 1.05 rad of flexion. The start angle (1.57 rad) was positioned just beyond the vertical alignment of the lever arm so that the exercised leg was slightly extended. The stop angle (0.52 rad) was chosen as it allowed the quadriiceps to be exercised to fatigue and still exert torque at the extreme range of motion. As the exercise involved moving the limb through a gravity dependent position, additional force was required to accelerate the limb. Correction for gravity was made by using the dynamometer's gravity correction procedure which accounted for the gravitational effects of the subject's limb and lever arm. Also, for reliability, the same gravity correction factor obtained during the initial test was used for each subsequent test.

Experimental procedure
On their arrival at the laboratory, the stature and body mass of the participants were recorded; they were then fully accustomed to the dynamometer and the testing procedures. The experiment was conducted over a five day period, with days 2 and 4 as rest days. All participants were instructed to abstain from exercise during the five days of the experiment. On the first day, concentric peak torque of the preferred leg was assessed at angular velocities of 0.52, 1.05, 2.09, and 3.14 rad/s, and peak torque (N.m), angle of peak torque (rad), and mean torque (N.m) for each velocity were recorded as baseline. Participants then performed, in a randomised manner, 16 fatiguing bouts of maximal intensity exercise, four bouts at each velocity (as shown in figure 1). To accomplish this, five fatiguing bouts and their subsequent exercise measurements were performed on day 1 after the pre-baseline measures were recorded, six on day 3, and the five remaining bouts were performed on the fifth day. Post-baseline measures were also taken on the fifth day to identify possible adaptation.

Before each bout, participants warmed up by running on a treadmill (Powerjog, GXC200) for five minutes at a self-selected speed. The speed selected on this initial occasion was used for each subsequent occasion. Before any measurements, five warm up repetitions were performed to accustom participants to the velocity at which they were about to exercise to induce fatigue. For each exercise bout, participants placed their hands on their hips for stabilisation and maximally exercised the quadriiceps of their preferred leg in the concentric (shortening) mode of action. To address the stretch-shorten cycle characteristic inherent in muscle, participants were instructed to produce torque in a smooth continuous action and not to kick back at the beginning phase of muscle action. The exercised limb was passively returned to the starting position at the same velocity to ensure that the muscle was exercised in only the concentric mode of action. To ensure maximum effort, the touch screen monitor was placed so that the subject could view a histogram illustration of peak torque output for each repetition, and verbal encouragement was given throughout. On completion of the fatiguing bout, the participant remained in position for 45 seconds and was then instructed to perform one maximal effort at one of the four velocities. A warm down was performed on the treadmill for five minutes after each bout of exercise, and a rest of 20 minutes was implemented between bouts to allow full recovery.

Calculations of work
An effort was made to equate the work rates of the prior exercise bouts so that a similar degree of fatigue was experienced at each velocity. From the equation

\[ s = \frac{r \theta \pi}{180} = 0.017453293 \cdot r \cdot \theta \]

(where \( \theta \) is the range of motion (60°), \( r \) is the lever arm length (29–35 cm, dependent on subject leg length), \( s \) is the angular distance (arc)), the distance of the angular motion of the leg multiplied by the mean torque of the prior baseline gave the work rate for one repetition. Fifteen repetitions were chosen at 0.52 rad/s, and the number of repetitions for each of the three remaining velocities was calculated using the same equation. This was accomplished by multiplying the distance of angular motion by the corresponding baseline mean torque outputs for that velocity, then dividing this figure into the work rate for 0.52 rad/s to derive the number of repetitions for that velocity.
Given that less torque was produced at higher velocities, more repetitions were performed with increases in velocity to ensure that the amount of work was similar between fatiguing bouts. The number of repetitions ranged from 15 at the low velocities to 26 at the highest velocity. As this method only allowed the amount of work to be estimated, for meaningful comparisons, mean mechanical work performed for all fatiguing bouts was held at 3050–3150 J.

**Statistical analysis**

Using pre-baseline as a covariate, an analysis of covariance was used to compare torque-velocity relations. Dependent variables were analysed by one factor, within subject analysis of variance with repeated measures. Related ttests with Bonferroni correction identified where significant differences occurred. Significance was accepted at $p<0.05$.

**RESULTS**

Tables 1 and 2 present a summary of group mean (SEM) results of all exercise protocols on mean torque, peak torque, and angle of peak torque at 0.52 and 1.05 rad/s.

| Table 1 Summary of group mean (SEM) results of all exercise protocols on mean torque, peak torque, and angle of peak torque at 0.52 and 1.05 rad/s |
|---|---|---|---|---|---|
| 0.52 | 1.05 | 0.52 | 1.05 | 0.52 | 1.05 |
| Mean torque (N.m) | Peak torque (N.m) | Angle of peak torque (rad) | Mean torque (N.m) | Peak torque (N.m) | Angle of peak torque (rad) |
| Baseline | 255.84 (15.41) | 314.42 (12.87) | 0.31 (0.04) | 232.44 (16.75) | 286.30 (15.41) | 0.38 (0.04) |
| 0.52 | 202.42 (15.41) | 250.67 (11.99) | 0.37 (0.06) | 178.20 (15.32) | 218.04 (17.11) | 0.36 (0.07) |
| 1.05 | 222.00 (15.13) | 274.15 (13.32) | 0.35 (0.05) | 192.88 (13.36) | 236.77 (11.46) | 0.42 (0.07) |
| 2.09 | 225.76 (14.29) | 261.23 (15.04) | 0.32 (0.05) | 198.87 (14.36) | 242.90 (12.43) | 0.34 (0.06) |
| 3.14 | 228.05 (13.35) | 263.08 (13.26) | 0.31 (0.05) | 204.71 (13.67) | 251.61 (13.17) | 0.38 (0.07) |
| Post-baseline | 256.39 (17.04) | 308.20 (18.08) | 0.39 (0.05) | 231.48 (18.80) | 280.83 (18.74) | 0.34 (0.05) |

Figures 2–4 show comparisons of group mean results for peak torque (N.m), angle of peak torque (rad), and mean torque (N.m).

**Peak torque**

Peak torque (fig 2) in subsequent exercise was less than baseline at 0.52 rad/s after fatiguing exercise at 0.52 rad/s ($p<0.05$). The subsequent exercise at 1.05 rad/s led to reductions between baseline and fatigueg exercise at 0.52 and 1.05 rad/s ($p<0.05$). The subsequent exercise at 2.09 rad/s led to a greater reduction between baseline and all measures of fatigue ($p<0.05$), and subsequent exercise at 3.14 rad/s after fatiguing exercise at 0.52, 1.05, and 3.14 rad/s was also accompanied by reductions ($p<0.05$).

**Angle of peak torque**

Angles (fig 3) at which peak torque occurred were not velocity dependent and did not differ from baseline and subsequent exercise measures ($p>0.05$).

**Mean torque**

Mean torque (fig 4) in subsequent exercise at 0.52 rad/s after fatiguing exercise at 0.52 and 1.05 rad/s was less than baseline ($p<0.05$), and subsequent exercise at 1.05 rad/s led to reductions between baseline and fatiguing exercise at 0.52 and 1.05 rad/s ($p<0.05$). The subsequent exercise at 2.09 and 3.14 rad/s led to reductions between baseline and all fatiguing exercise measures ($p<0.05$).
Dysfunction of the type I fibres was proposed to explain the observed velocity dependency of torque output by MIE at all velocities, although the relative contributions of slow twitch during low velocity exercise and fast twitch during high velocity exercise vary with the type of prior exercise. In MIE, all fibre types contribute to torque at low and high velocities, although, because of the greater number of cross bridge interactions at the lower velocities, more torque is produced. As the larger fast twitch fibres contain more protein filaments, they have greater torque generating potential. Also, as they use the anaerobic glycolysis system and have a more extensive sarcoplasmic reticulum, which in turn allows a more rapid release of calcium ions across the sarcolemma, they can generate torque more rapidly. Thus, during maximal exercise at all velocities the relative contribution of the fast twitch fibres is increased compared with exercise at the same velocity in submaximal exercise. This would influence the amount of fatigue experienced during maximal exercise at the lower velocities.

Research has also highlighted that the maximum shortening velocity of muscle is related to the rate at which the cross bridges cycle, irrespective of the number of cross bridges interacting and sarcomere length. Every actin-myosin interaction requires the hydrolysis of one molecule of ATP. As torque declines linearly with increases in the velocity of action, then as the velocity of exercise increases, less ATP is hydrolysed per repetition. As the type II fibres consume ATP at a greater rate and more is hydrolysed at the lower velocities, more metabolic acidosis will occur. This decreases sodium and calcium ion release, which in turn results in a decline in potassium concentration and ultimately restricts cross bridge kinetics. Therefore, as the fast twitch muscle fibres predominate for each velocity of prior exercise, fatigue during maximal exercise may be related to the amount of torque generated rather than the velocity at which the force is being generated.

It has been proposed that, during repetitive concentric exercise, the pattern of the firing frequencies can be altered. Indeed, research has indicated that slow twitch motor units fire continuously for long periods, whereas the fast twitch motor units fire at high rates, but only intermittently. In mixed muscle such as is typically observed in the human quadriceps, maximal torque is produced when both slow and fast twitch pools of motor units are recruited at an optimal rate coding to produce a fused tetanus synchronously. If one type of motor unit cannot initiate optimal delivery of nerve signals to muscle fibres, optimal recruitment of muscle fibres for maximal force production is diminished. Therefore, another reason why fatigue in MIE could be greater at lower velocities is that each repetition requires the activation of muscle fibres for a greater duration over the same range of motion. The experience of fatigue may cause greater disruption to the synchronous behaviour of the motor unit’s firing frequencies throughout each repetition and from one repetition to the next.

A further possible reason why low velocity prior exercise causes greater decline in torque output is central fatigue. During the testing procedures, volunteers reported that a greater degree of psychological rather than muscular discomfort occurred at the lower velocities. Central fatigue is determined by a dysfunction within the neural pathways that send and receive command signals to and from the muscle. It has been proposed that central fatigue is caused by inhibition of the recruitment of motor areas as the result of nervous impulses.
from the chemoreceptors in the fatigued muscles. Central fatigue in maximal exercise may be caused by inhibition of voluntary effort because of the discomfort in the muscle.

It should be noted that during the experimental protocol every participant was encouraged by vocal and visual (force histogram) stimuli for every repetition. Another possible limitation is the effect of breath holding (valsalva manoeuvre) during the fatiguing and subsequent maximal actions, which is difficult to control. This could increase muscle acidity during exercise, which would interfere with torque production, especially during the longer duration, low velocity exercise.

In this study, subsequent exercise was more diminished at the higher velocities after low and high velocity fatiguing bouts of exercise. The more decisive effect of fatigue at higher velocities on subsequent exercise is perhaps due to greater exhaustion of more muscle fibres. Specifically, the fatigue sensitive type II fibres at the onset of acidosis would interfere with exhaustion of more muscle fibres. The greater fatigue experienced during low velocity subsequent exercise is perhaps due to greater exhaustion of more muscle fibres.


The finding that low velocity exercise reduces torque at high velocities more than at low velocities could be attributable to recruitment of both type I and type II muscle fibres. This produces greater metabolic acidosis than higher velocities, during which mainly type II fibres are recruited, thus decreasing torque in subsequent exercise. The greater decline in torque during subsequent exercise at high velocities is perhaps due to greater exhaustion of more muscle fibres, specifically the fatigue sensitive type II fibres, whereas low velocity subsequent exercise is less affected because of greater use of the more fatigue resistant type I fibres.

**Take home message**

The finding that low velocity exercise reduces torque at high velocities more than at low velocities could be relevant to those who use isokinetic dynamometry for strength training, injury prevention, and rehabilitation.

**REFERENCES**